

FDR's RC stuff - Walkera DEVO 8 / 8S model configurator

Model Menu



Model Name:



Type Select



Helicopter



Airplane



Trim System

Elevator Step: / 20 Limited:

Aileron Step: / 20 Limited:

Rudder Step: / 20 Limited:

Throttle Step: / 20

Left Step: / 20

Right Step: / 20

Elevator Trim: %

Aileron Trim: %

Rudder Trim: %

Throttle Trim: %

Left Trim: %

Right Trim: %



Stick Position Switch

Stick Position Switch 0:

Channel:

On:

Position: %

Stick Position Switch 1:

Channel:



Device Select

Flight Mode Switch:

Throttle Hold Switch:

Stunt Trim Select:

Hovering Pitch:

Hovering Throttle:



Device Output

Gear:

Pitch:

AUX2:

AUX3:



Swash Type



1 Servo Normal



2 Servos 180°



3 Servos 120°



3 Servos 140°



3 Servos 90°



Power Amplifier



-5 dBm



0 dBm



+5 dBm



+10 dBm



+15 dBm



+20 dBm



Fixed ID

Active:

Function Menu



Reverse Switch

- Elevator:
- Aileron:
- Throttle:
- Rudder:
- Gear:
- Pitch:
- Gyro:
- AUX3:



Travel Adjust

- Elevator U: Elevator D:
- Aileron L: Aileron R:
- Throttle H: Throttle L:
- Rudder L: Rudder R:
- Gear +: Gear -:
- Pitch H: Pitch L:
- Gyro +: Gyro -:
- AUX3 +: AUX3 -:



Sub Trim

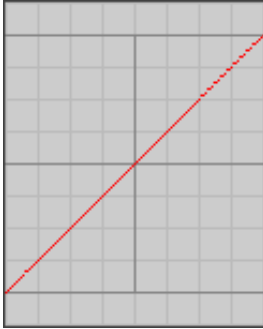
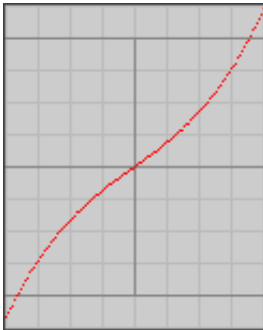
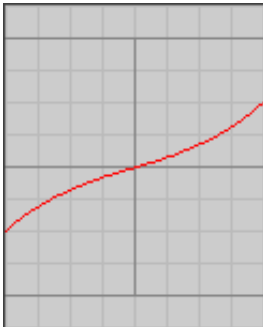
- Elevator: %
- Aileron: %
- Throttle: %
- Rudder: %
- Gear: %
- Pitch: %
- Gyro: %
- AUX3: %

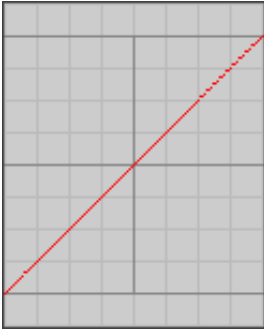


Dual Rate

Elevator Channel

- Normal Mode:
- Stunt 1:
- Stunt 2:

Throttle Hold: **Pos 0:**D/R L: D/R H: Exp L: Exp H: **Pos 1:**D/R L: D/R H: Exp L: Exp H: **Pos 2:**D/R L: D/R H: Exp L: Exp H: **Pos 3:**D/R L: D/R H: Exp L: Exp H:



Aileron Channel

Normal Mode:

Stunt 1:

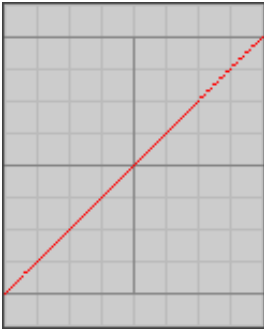
Stunt 2:

Throttle Hold:

Pos 0:

D/R L: D/R H:

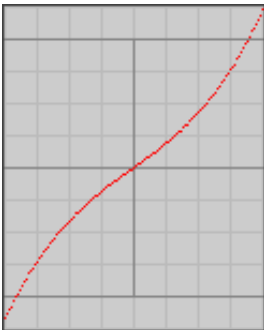
Exp L: Exp H:



Pos 1:

D/R L: D/R H:

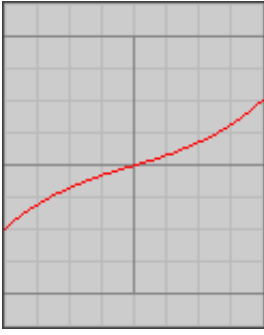
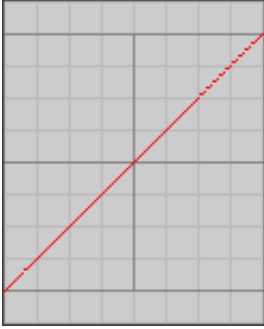
Exp L: Exp H:



Pos 2:

D/R L: D/R H:

Exp L: Exp H:

**Pos 3:**D/R L: D/R H: Exp L: Exp H: **Rudder Channel****Throttle Hold**Active: Position: %**Throttle Curve****Normal Mode**Exp: **Point L 0.0%:**Output: %**Point 1 16.5%:**Output: % Hovering: **Point 2 33.5%:**Output: % Hovering: **Point M 50.0%:**

Output: % Hovering:

Point 3 66.5%:

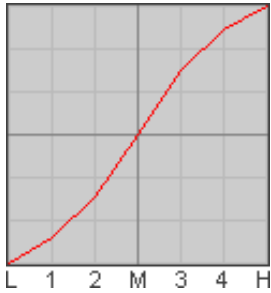
Output: % Hovering:

Point 4 83.5%:

Output: % Hovering:

Point H 100.0%:

Output: %



Stunt 1

Exp:

Point L 0.0%:

Output: %

Point 1 16.5%:

Output: % Hovering:

Point 2 33.5%:

Output: % Hovering:

Point M 50.0%:

Output: % Hovering:

Point 3 66.5%:

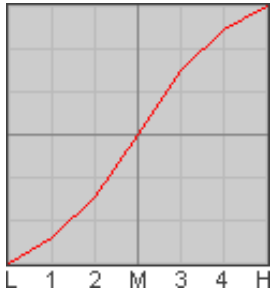
Output: % Hovering:

Point 4 83.5%:

Output: % Hovering:

Point H 100.0%:

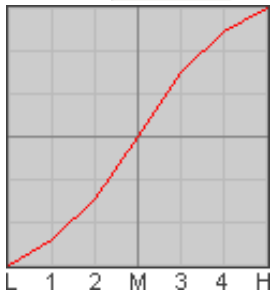
Output: 100 %

**Stunt 2**Exp: **Point L 0.0%:**

Output: 0 %

Point 1 16.5%:Output: 9,5 % Hovering: **Point 2 33.5%:**Output: 25,5 % Hovering: **Point M 50.0%:**Output: 50 % Hovering: **Point 3 66.5%:**Output: 74,5 % Hovering: **Point 4 83.5%:**Output: 90,5 % Hovering: **Point H 100.0%:**

Output: 100 %





Mix to Throttle

Elevator Channel

Always On

Normal Mode

Stunt 1

Switch: Stunt 2

Up: 0 Down: 0

Aileron Channel

Always On

Normal Mode

Stunt 1

Switch: Stunt 2

Left: 0 Right: 0

Rudder Channel

Always On

Normal Mode

Stunt 1

Switch: Stunt 2

Left: 0 Right: 0



Gyro Sensor

Channel: Manual

Switch: ELEV-D/R FMOD SW

Pos 0 / Normal: 34 %

Pos 1 / Stunt 1: 66 %

Pos 2 / Stunt 2: 34 %



Governor

Normal Mode: 0 %

Stunt 1: 0 %

Stunt 2: 0 %

Throttle Hold: 0 %



Swash Mix

Aileron: 60 %

Elevator: 60 %

Pitch: 60 %

Exponential:



Pitch Curve

Normal Mode

Exp:

Point L -100%:

Output: %

Point 1 -67%:

Point 2 -33%:

Point M 0%:

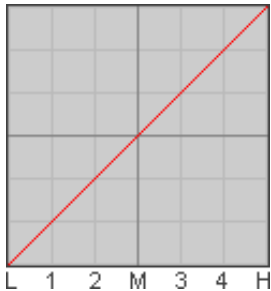
Output: % Hovering:

Point 3 +33%:

Point 4 +67%:

Point H +100%:

Output: %



Stunt 1

Exp:

Point L -100%:

Output: %

Point 1 -67%:

Point 2 -33%:

Point M 0%:

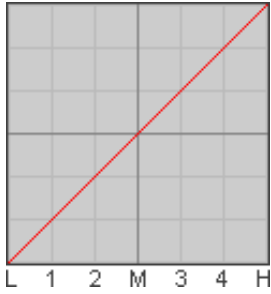
Output: % Hovering:

Point 3 +33%:

Point 4 +67%:

Point H +100%:

Output: %



Stunt 2

Exp:

Point L -100%:

Output: %

Point 1 -67%:

Point 2 -33%:

Point M 0%:

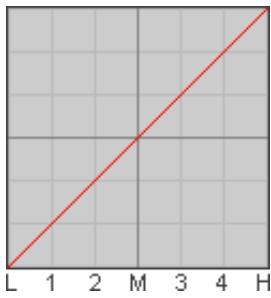
Output: % Hovering:

Point 3 +33%:

Point 4 +67%:

Point H +100%:

Output: %



Program Mix

Program Mix 1

Program Mix 2

Program Mix 3

Program Mix 4

Program Mix 5

Program Mix 6

Program Mix 7

Program Mix 8



Fail Safe

Elevator: Fail Safe:

Aileron: Fail Safe:

Throttle: Fail Safe:

Rudder: Fail Safe:

Gear:

Pitch: Fail Safe:

Gyro:

AUX3:



Trainer

Switch:

Elevator:

Aileron:

Throttle:

Rudder:

Gear:

Pitch:

Gyro:

AUX3:



Timer

Timer 1:

Switch:

Set Time: min sec

Timer 2:

Switch:

Like

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