1. „FIRMWARE FLASHEN“
2. MANUAL BAUT RATE 256000

3. Load Firmware
4. „FIRMWARE“ AUSWÄHLEN

5. ÖFFNEN
6. "FLASH Firmware"
7. "FLASHEN ERFOLGREICH"

8. "CONNECT"
9. „RESET SETTINGS“

10. „RESTORE“
11. „CONFIG.TXT“ AUSWÄHLEN

12. ÖFFNEN
13. CALIBRATE ACCELEROMETER

14. DISCONNECT
Setup

- Calibrate Accelerometer
- Calibrate Magnetometer
- Reset Settings
- Backup
- Restore

Place board or frame on leveled surface, proceed with calibration, ensure platform is not moving during calibration period.

Move multicopter at least 360 degrees on all axis of rotation, you have 30 seconds to perform this task.

Restore settings to default.

Backup your configuration in case of an accident, CLI settings are not included - See 'dump cli command.'

Heading: 56 deg
Pitch: 0 deg
Roll: -0.2 Deg

Reset 2 axes, offset: 0 deg

Info
- Battery voltage: 0 V
- Capacity drawn: 0 mAh
- Current draw: 0.30 A
- RSS: 0 %

GPS
- 3D Fix
- Sat: 
- Latitude: 
- Longitude: 

Instruments

FINISH